

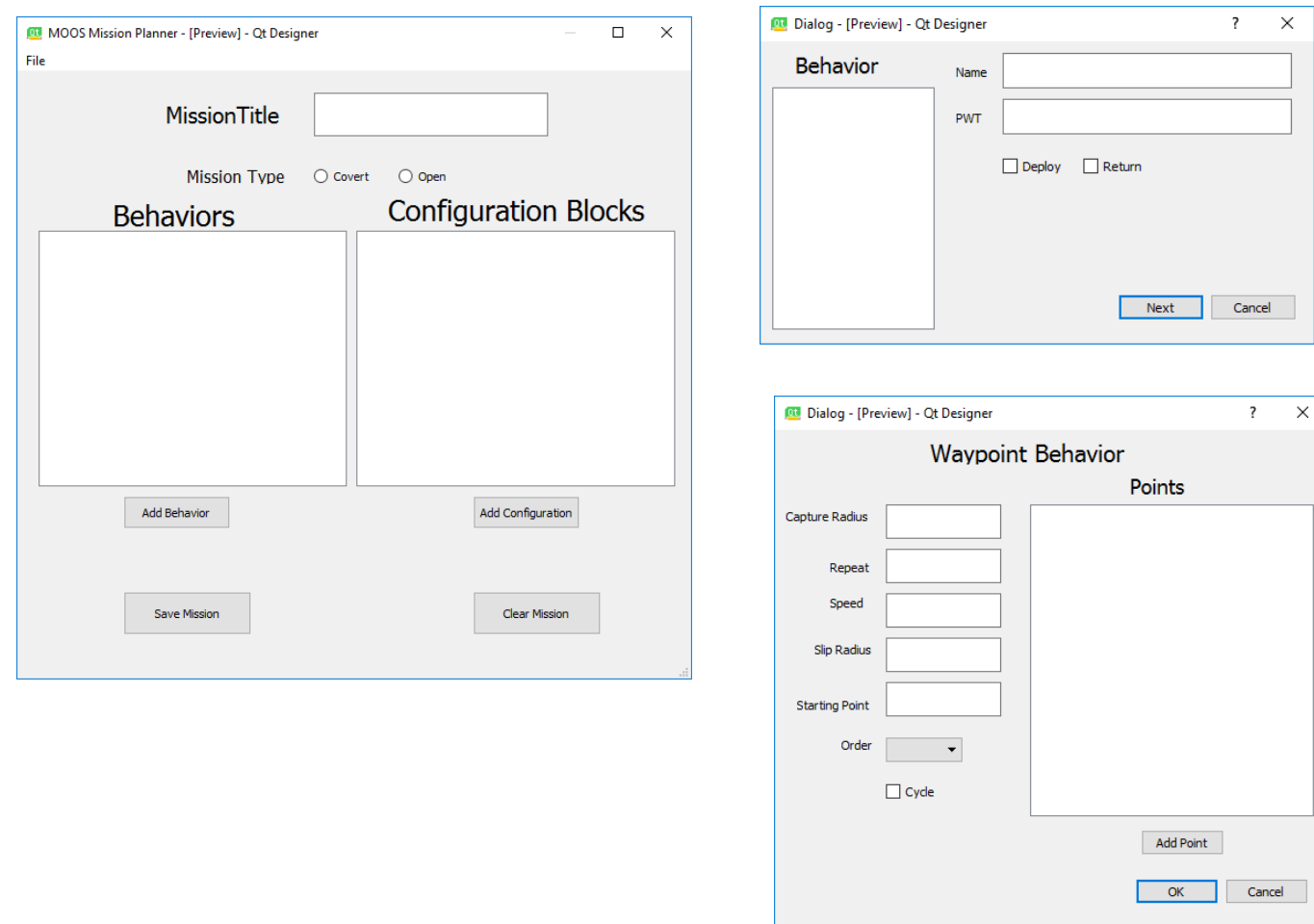
S.A.T.I.R.E. Autonomous Underwater Vehicle

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Introduction

- The SATIRE project is a covert AUV for the purpose of remote observation.
- The AUV is intended to collect data from multiple sensors that will be collected in an onboard database.
- The device will operate based on a pre-planned mission script.



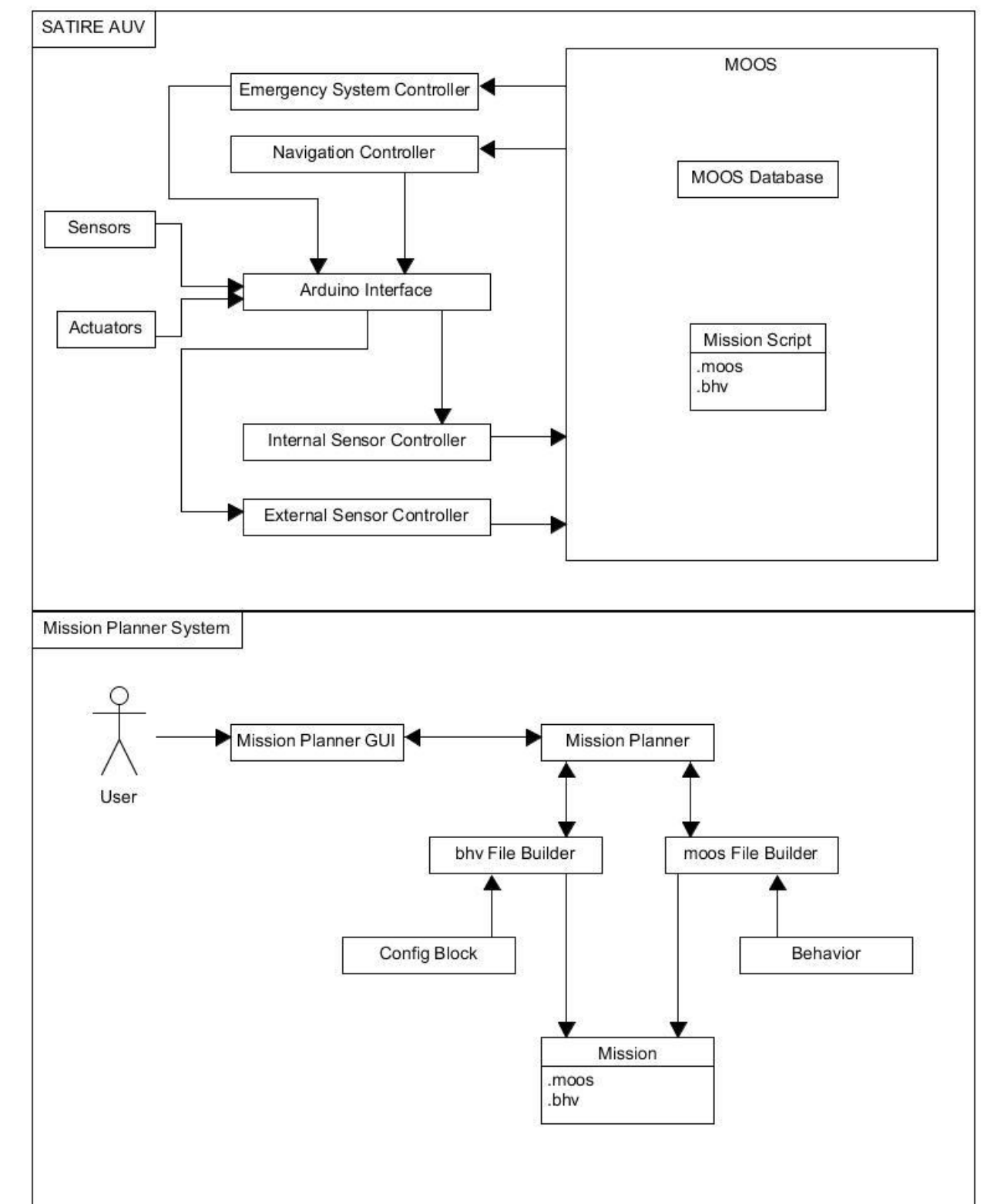
Approach

- Uses the Mission Orientation Operating System developed by MIT and Oxford for AUVs as the system OS.
- Sensor data is sent from an Arduino board into the MOOS Database, and received by subscribing modules.
- A mission planner is used for automated mission script generation.

Features

- Fully autonomous operation of a predefined mission plan.
- Emergency response system to detect system malfunctions and take actions base on the mission type.
- Use of a windows application for the creation of mission scripts.

System Architecture



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